

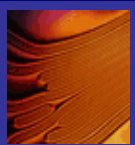


Liquid Crystal Elastomer Dielectric Constant Measurements

Jeremy Neal

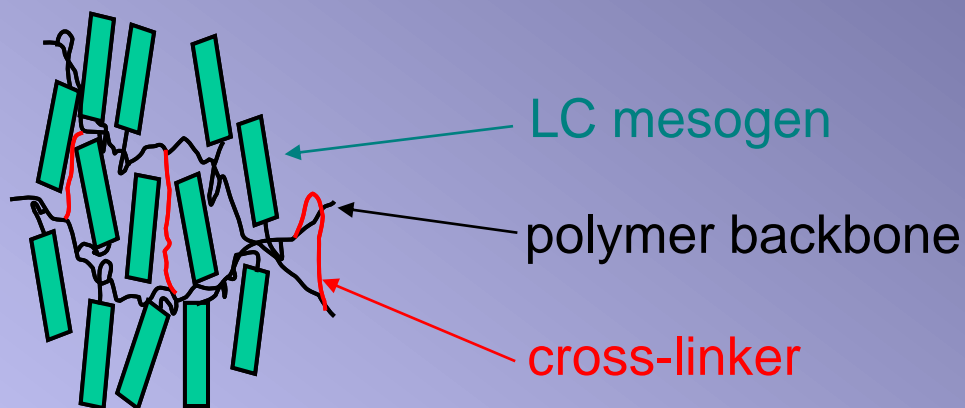
P.Palffy-Muhoray

*Liquid Crystal Institute
Kent State University
Kent, Ohio*



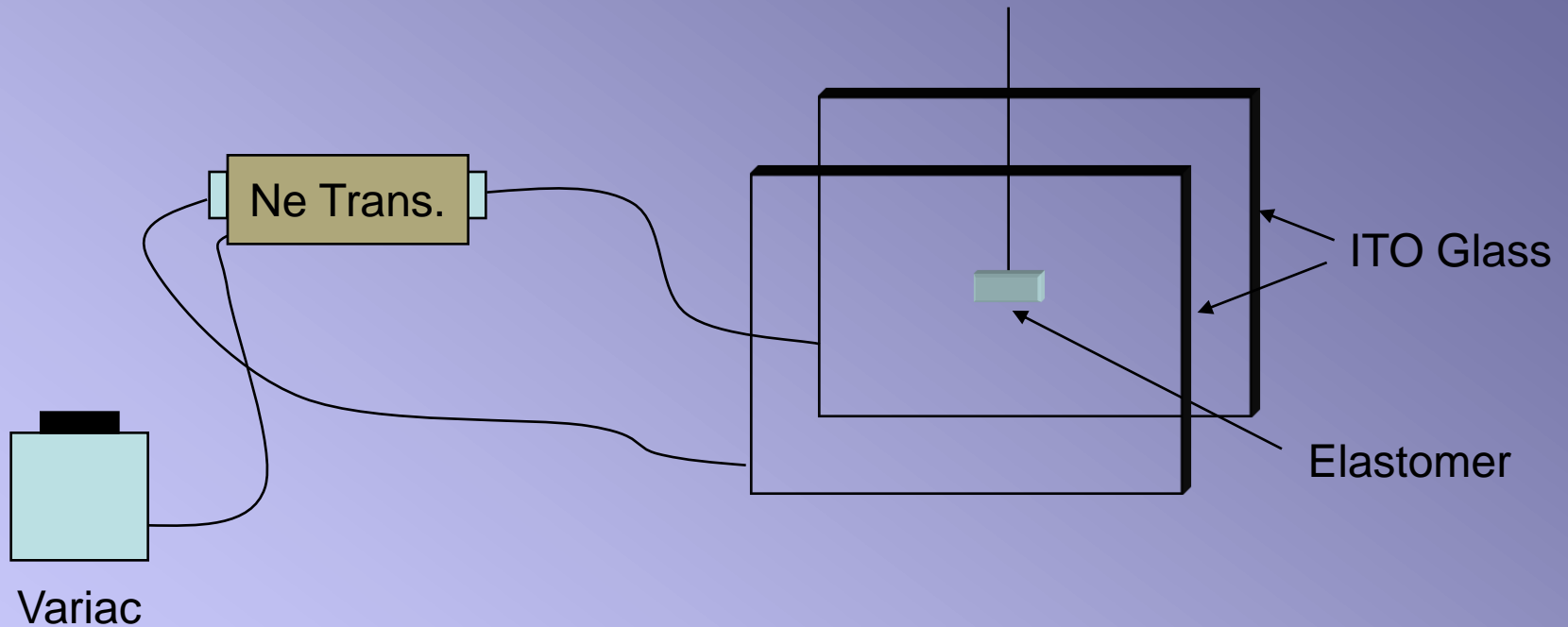
Liquid Crystal Elastomers

- liquid crystal + rubber



- LC nematic monodomain
- synthesize here - need to characterize

Experiment 1



Elastomer is suspended on a string between two parallel pieces of ITO coated glass. Elastomer aligns along sufficiently strong applied field.



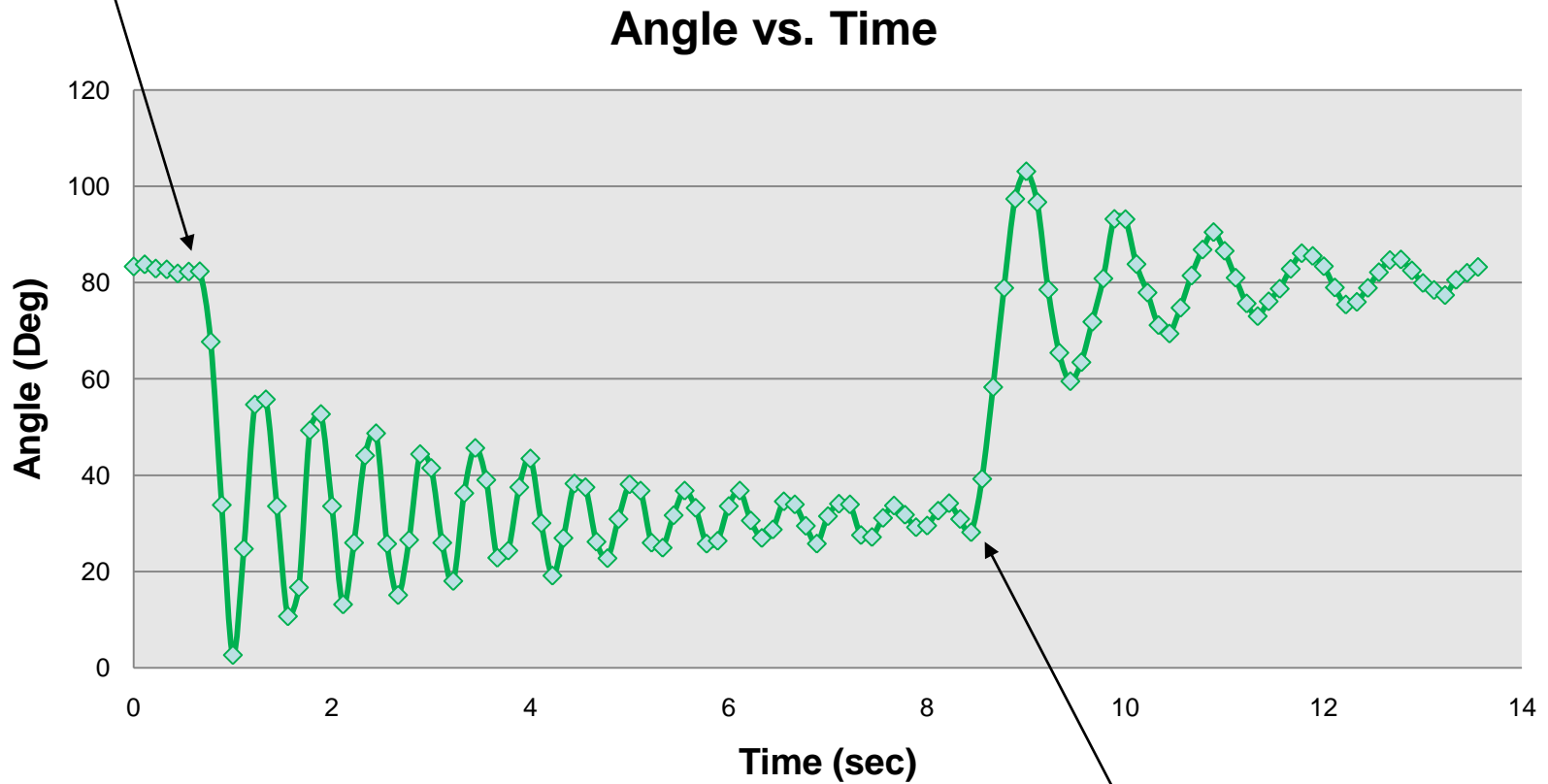
Video of Experiment





Experimental Data

Field On



Field Off



Overview

Want to solve

$$\tau = I \frac{d^2\theta}{dt^2} = \frac{d\xi}{d\theta}$$

τ – torque

ξ – energy

I – moment of inertia



*Directly from
experimental data*

Depends on:

$\left. \begin{array}{l} \varepsilon_{\square} \\ \varepsilon_{\perp} \end{array} \right\}$ – dielectric constant components

k – spring constant
material properties



Theory

Energy of elastomer:

$$\xi = -\frac{V}{2} \vec{D} \cdot \vec{E} - \frac{1}{2} k \theta^2$$

k - spring constant

$$= -\frac{V}{2} \left[\epsilon_0 (1 + \chi) \vec{E} \right] \cdot \vec{E} - \frac{1}{2} k \theta^2$$

V - volume

χ - susceptibility

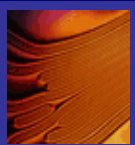
$$= -\frac{V}{2} \left[\epsilon_0 \vec{E} + \vec{P} \right] \cdot \vec{E} - \frac{1}{2} k \theta^2$$

\vec{P} - polarization

orientationally invariant

$$= -\frac{V}{2} \left[\epsilon_0 E^2 + \vec{P} \cdot \vec{E} \right] - \frac{1}{2} k \theta^2$$

$$= -\frac{V}{2} \vec{P} \cdot \vec{E} - \frac{1}{2} k \theta^2$$



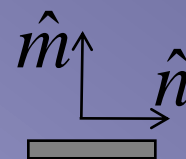
Theory

In general:

$$\vec{P} = \rho \vec{\alpha} \vec{E}^{loc}$$

$$= \rho \alpha_{\parallel} E_{\parallel}^{loc} \hat{n} + \rho \alpha_{\perp} E_{\perp}^{loc} \hat{m}$$

$$= \left(\rho \alpha_{\parallel} \hat{n} \hat{n} + \rho \alpha_{\perp} (\vec{I} - \hat{n} \hat{n}) \right) \vec{E}^{loc}$$



α – polarizability

ρ – density

where

$$\vec{E}_{loc} = \vec{E}_{app} - \mathbf{N} \frac{\vec{P}}{\epsilon_0}$$

N – depolarizing tensor

$$= \left(\vec{E}_{app} - N_{\parallel} \frac{\vec{P}}{\epsilon_0} \right) \hat{n} \hat{n} + \left(\vec{E}_{app} - N_{\perp} \frac{\vec{P}}{\epsilon_0} \right) (\vec{I} - \hat{n} \hat{n})$$



Theory

cont'd

$$\vec{P} = \rho\alpha_{\parallel} \left(\vec{E}_{app} - \mathbf{N}_{\parallel} \frac{\vec{P}}{\epsilon_0} \right) \hat{n}\hat{n} + \rho\alpha_{\perp} \left(\vec{E}_{app} - \mathbf{N}_{\perp} \frac{\vec{P}}{\epsilon_0} \right) (\vec{I} - \hat{n}\hat{n})$$

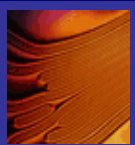
$$\vec{P} \left(\vec{I} \left(1 + \frac{\alpha_{\perp} \mathbf{N}_{\perp} \rho}{\epsilon_0} \right) + \frac{\rho}{\epsilon_0} (\alpha_{\parallel} \mathbf{N}_{\parallel} - \alpha_{\perp} \mathbf{N}_{\perp}) \hat{n}\hat{n} \right) = \left((\alpha_{\parallel} - \alpha_{\perp}) \hat{n}\hat{n} + \alpha_{\perp} \vec{I} \right) \rho \vec{E}_{app}$$

Make substitutions:

$$a = \left(1 + \frac{\alpha_{\perp} \mathbf{N}_{\perp} \rho}{\epsilon_0} \right) \quad b = \frac{\rho}{\epsilon_0} (\alpha_{\parallel} \mathbf{N}_{\parallel} - \alpha_{\perp} \mathbf{N}_{\perp})$$

then

$$\vec{P} (a\vec{I} + b\hat{n}\hat{n}) = \left((\alpha_{\parallel} - \alpha_{\perp}) \hat{n}\hat{n} + \alpha_{\perp} \vec{I} \right) \rho \vec{E}_{app}$$



Theory

$$\vec{P}(a\vec{I} + b\hat{n}\hat{n}) = ((\alpha_{||} - \alpha_{\perp})\hat{n}\hat{n} + \alpha_{\perp}\vec{I})\rho\vec{E}_{app}$$

Choose A & B such that

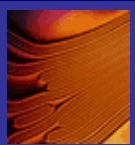
$$(a\vec{I} + b\hat{n}\hat{n})(A\vec{I} + B\hat{n}\hat{n}) = \vec{I}$$

then

$$A = \frac{1}{a} \quad B = -\frac{b}{a(a+b)} \quad A + B = \frac{1}{a+b}$$

$$\vec{P} = (A\vec{I} + B\hat{n}\hat{n})((\alpha_{||} - \alpha_{\perp})\hat{n}\hat{n} + \alpha_{\perp}\vec{I})\rho\vec{E}_{app}$$

$$\vec{P} = (\rho\alpha_{\perp}A\vec{I} + (B\rho\alpha_{\perp} + (A+B)\rho(\alpha_{||} - \alpha_{\perp}))\hat{n}\hat{n})\vec{E}_{app}$$



Theory

Recall

$$\xi = -\frac{V}{2} \vec{P} \cdot \vec{E} - \frac{1}{2} k \theta^2$$

Thus *orientationally invariant*

$$\begin{aligned} \xi &= -\frac{V}{2} \left[\cancel{\rho g a_{\perp}} \overrightarrow{A E_{app}^2} + (B \rho \alpha_{\perp} + (A + B) \rho (\alpha_{\parallel} - \alpha_{\perp})) \cos^2 \theta E_{app}^2 \right] - \frac{1}{2} k \theta^2 \\ &= -\frac{V}{2} (B \rho \alpha_{\perp} + (A + B) \rho (\alpha_{\parallel} - \alpha_{\perp})) \cos^2 \theta E_{app}^2 - \frac{1}{2} k \theta^2 \end{aligned}$$

Want to solve

$$\tau = I \frac{d^2 \theta}{dt^2} = \frac{d\xi}{d\theta} \quad \tau - \text{torque}$$

$$\frac{d\xi}{d\theta} = (B \rho \alpha_{\perp} + (A + B) \rho (\alpha_{\parallel} - \alpha_{\perp})) V \cos \theta \sin \theta E_{app}^2 - k \theta$$



Theory

Also

$$\varepsilon_{||} = 1 + \frac{\rho \alpha_{||}}{\varepsilon_0}, \quad \varepsilon_{\perp} = 1 + \frac{\rho \alpha_{\perp}}{\varepsilon_0} \longrightarrow \alpha_{||} - \alpha_{\perp} = \frac{\varepsilon_0 (\varepsilon_{||} - \varepsilon_{\perp})}{\rho}$$

So

$$I \frac{d^2 \theta}{dt^2} = \frac{d\xi}{d\theta} = \left(B(\varepsilon_{\perp} - 1) + (A + B)(\varepsilon_{||} - \varepsilon_{\perp}) \right) V \varepsilon_0 \cos \theta \sin \theta E_{app}^2 - k\theta$$

where

$$B = \frac{(\varepsilon_{\perp} - 1)N_{\perp} - (\varepsilon_{||} - 1)N_{||}}{(1 + (\varepsilon_{||} - 1)N_{||})(1 + (\varepsilon_{\perp} - 1)N_{\perp})} \quad A + B = \frac{1}{1 + (\varepsilon_{||} - 1)N_{||}}$$

Need the following: $N_{||}, N_{\perp}$ – depolarizing factors

E_{app} – electric field

I – moment of inertia

$k, \varepsilon_{\perp},$ or $\varepsilon_{||}$ – free parameters



Depolarizing Factors

Assume depolarizing factors for an ellipse can be used:

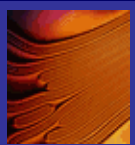
$$N_{\alpha} = \frac{a+b+c}{2} \int_0^{\infty} \frac{ds}{(\alpha^2 + s)\sqrt{(a^2 + s)(b^2 + s)(c^2 + s)}}$$

$\alpha = a, b, c$ *ellipse semi-axes*

$$a = 10\text{mm} \qquad N_{10} = N_{||} = .0076$$

$$b = 1.9\text{mm} \longrightarrow N_{1.9} = .0922$$

$$c = .22\text{mm} \qquad N_{.2} = N_{\perp} = .9002$$



Elastomer Properties



$$l = 2.00 \text{ cm}$$

$$w = 3.8 \text{ mm}$$

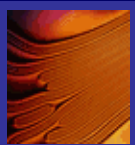
$$d = .43 \text{ mm}$$

$$m = .386 \text{ g}$$

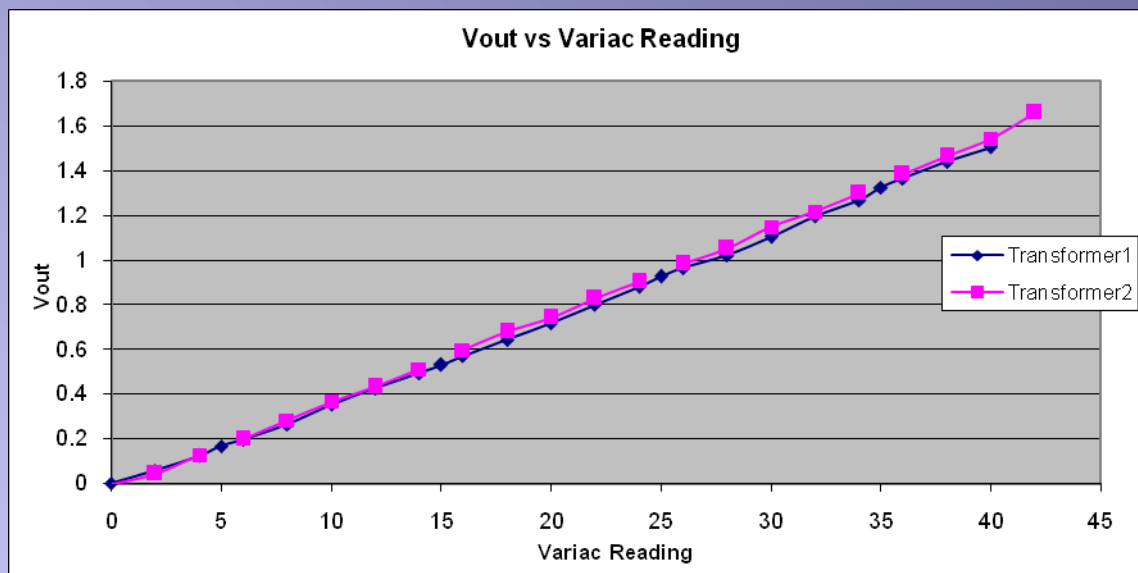
$$I = \frac{1}{12} m(d^2 + l^2)$$

$$= 1.29 \times 10^{-9} \text{ kg m}^2$$

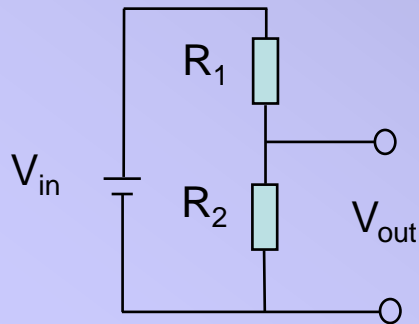
$$V = 3.28 \times 10^{-8} \text{ m}^3$$



Electric Field Measurement



Voltage divider:



$$R_1 = 98.55 \text{ M}\Omega$$

$$R_2 = 26,800 \text{ }\Omega$$

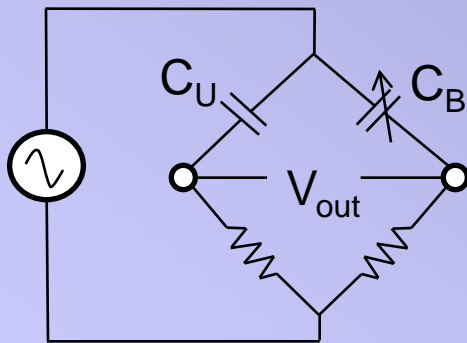
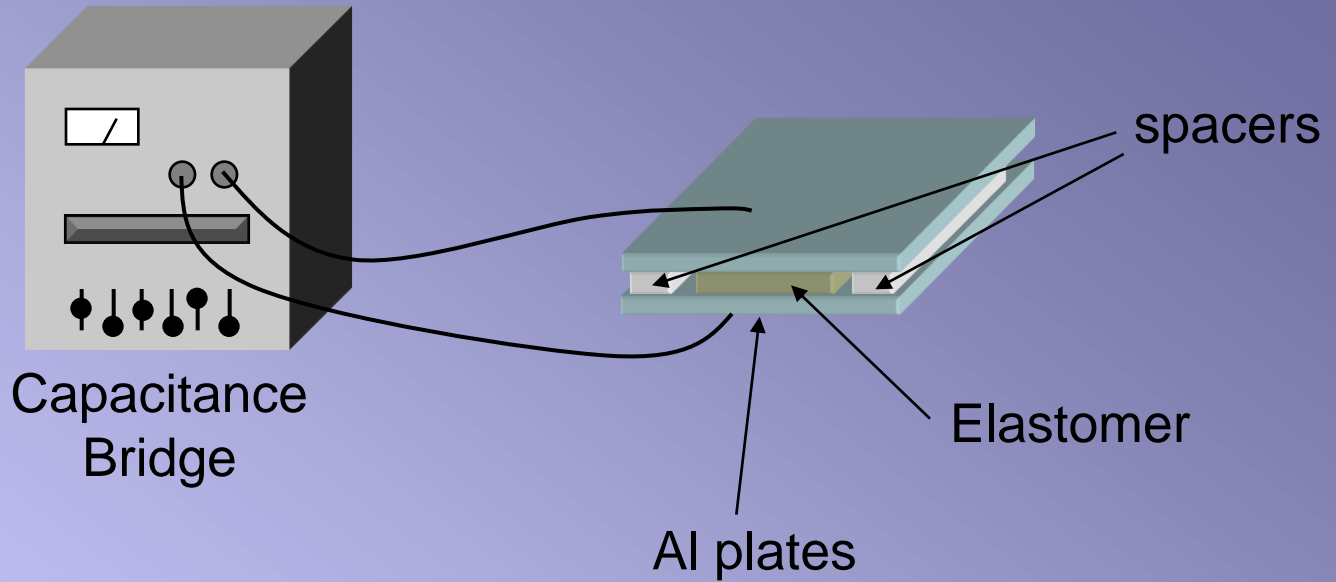
$$V_{in} (110) = 15,206 \text{ V}$$

$$V_{in} (140) = 19,353 \text{ V}$$

Thus

$$E_{app} = 5.95 \times 10^5 \text{ V/m}$$

Experiment 2



Elastomer is sandwiched between aluminum plates and capacitance is measured with bridge



Theory & Results

Without elastomer:

$$C_{tot} = \frac{\epsilon_s \epsilon_0 A_s}{d} + \frac{\epsilon_{air} \epsilon_0 A_{air,1}}{d}$$

Using

$$\epsilon_{air} = 1.00059$$

Find

$$\epsilon_s = 3.88$$

With elastomer:

$$C_{tot} = \frac{\epsilon_s \epsilon_0 A_s}{d} + \frac{\epsilon_{air} \epsilon_0 A_{air,2}}{d} + \frac{\epsilon_{\perp} \epsilon_0 A_e}{d}$$

Find

$$\epsilon_{\perp} = 3.38$$



Results

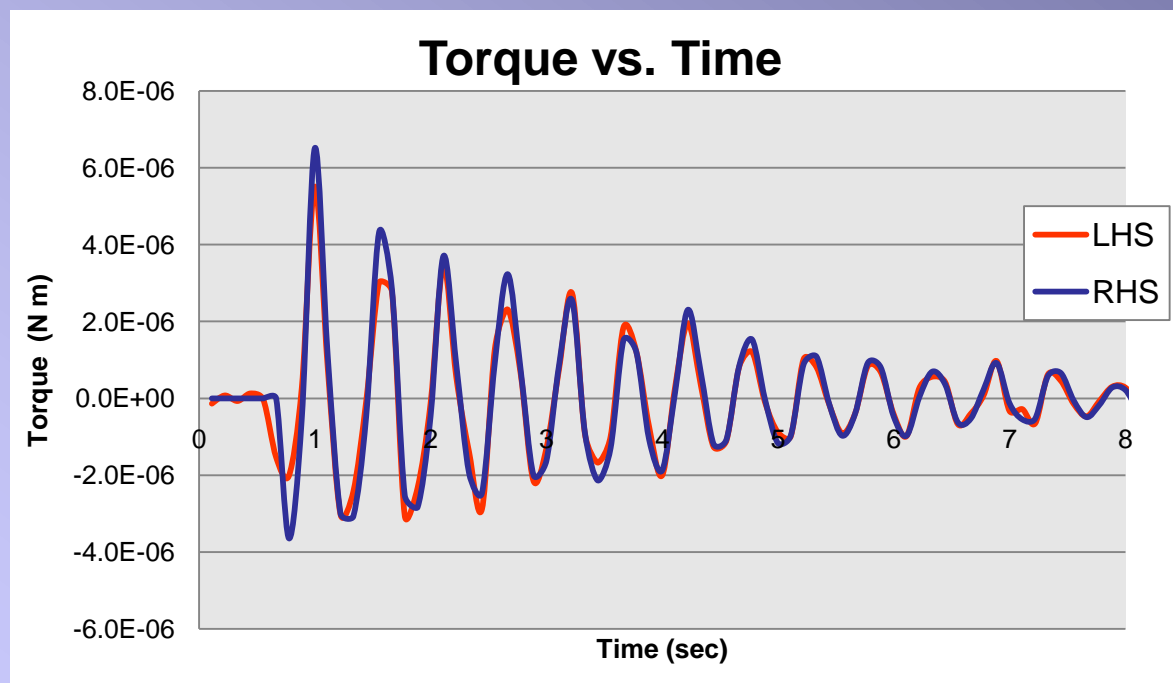
$$\tau = I \frac{d^2\theta}{dt^2} = \frac{d\xi}{d\theta}$$

LHS RHS

Using: $\varepsilon_{\square} = 3.29$

$\varepsilon_{\perp} = 3.38$

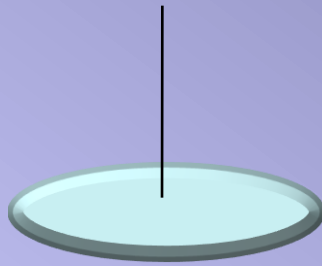
$k = 1.13 \times 10^{-8} \text{ N/m}$



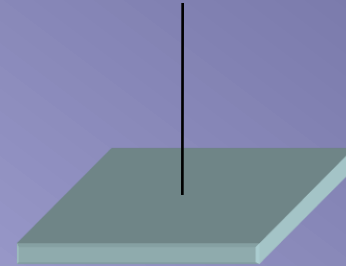


Possible Future Work

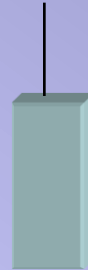
- Remove shape effects:



OR



- Remove anisotropy effects:



- Repeat experiments in magnetic field



Conclusions

- Electric field response used to determine elastomer dielectric constant values
- Would like to do similar magnetic field measurements
- Still a work in progress